

## 7.6 Surface integrals of vector fields

We learn

- an integral of a vector field  $F$  over a parametrized surface
- Interpretation of this integral as flux across the surface
- What an orientation of a surface is
- Some surfaces cannot be oriented
- How a parametrization determines an orientation
- Practice evaluating these integrals

What we can do without:

- Most of the formulas at the end of 7.6, on page 411.
- It is not worth remembering special formulas for surfaces that are graphs, or for spheres.

## The definition

We take

- a vector field  $F : \mathbb{R}^3 \rightarrow \mathbb{R}^3$
- a parametrized surface  
 $\Phi : D \rightarrow \mathbb{R}^3$  with  $\Phi(D) = S$

We define what the book calls the surface integral of  $F$  over  $\Phi$ . I would prefer to call it the integral of the flux form of  $F$ , or the flux integral of  $F$ .

$$\iint_{\Phi} F \cdot d\underline{S} = \iint_D F \cdot (\underline{T}_u \times \underline{T}_v) du dv$$

Later, when we know what an orientation of  $S$  is, we might write:

$$\iint_S F \cdot d\underline{S}$$

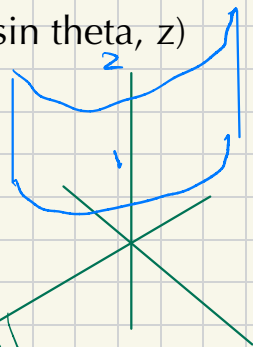
Example:

Find the flux of the vector field

$F(x,y,z) = (y z, x^2, x^2 y z)$  across the half-cylinder

$\Phi(\theta, z) = (2 \cos \theta, 2 \sin \theta, z)$

$0 \leq \theta \leq \pi, 1 \leq z \leq 2$



$$T_{\theta} = (-2 \sin \theta, 2 \cos \theta, 0)$$

$$T_z = (0, 0, 1)$$

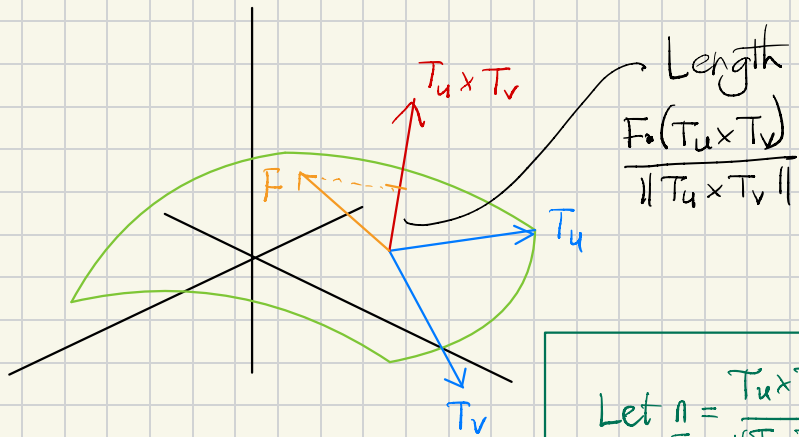
$$T_{\theta} \times T_z = (2 \cos \theta, 2 \sin \theta, 0)$$

The flux is

$$\int_1^2 \int_0^{\pi} (2 \sin \theta z, 4 \cos^2 \theta, 4 \cos^2 \theta 2 \sin \theta z) \cdot (2 \cos \theta, 2 \sin \theta, 0) d\theta dz$$

Answer 16/3

What does it mean?



$$\iint_D F \cdot (T_u \times T_v) \, du \, dv$$

$$= \iint_D \frac{F \cdot (T_u \times T_v)}{\|T_u \times T_v\|} \, du \, dv$$

$$= \iint_D F \cdot \underline{n} \, \|T_u \times T_v\| \, du \, dv = \int_S F \cdot \underline{n} \, dS$$

$$\underline{n} = \frac{T_u \times T_v}{\|T_u \times T_v\|}$$

This is a unit normal vector for S

# Pre-class Warm-up!!!

The picture on the left appeared at the end of class on Friday. Was it intended to help us understand

- how to set up an integral
- how to find the area of a surface
- what the flux of a vector field is
- ✓ why the the integral computes the flux of the vector field across the surface
- none of the above.

## The second half of section 7.6: Orientations

We learn:

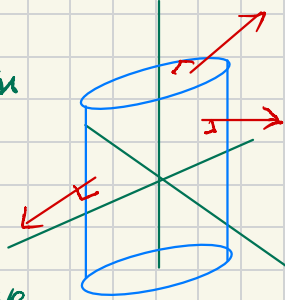
- what is an orientation?
- Descriptions like “the normal points out”.
- A parametrization determines an orientation
- Terminology: consistent or compatible with the orientation
- Unit normal
- We can only do flux integrals on orientable surfaces.
- Theoretical things, not proved: the integral does not depend on the choice of parametrization, provide it is consistent for the orientation.
- We don't need theorem 5 or Gauss's law of the special formulas that arise when the surface is a graph.
- Pages 410 and 411 we only need 1a and 1b.

## Orientation of surfaces

Definition: An orientation of a surface  $S$  is a continuous choice of a normal vector at each point of  $S$ .

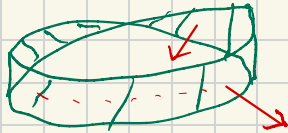
A cylinder has an orientation

This orientation points out.  
The orientation points in.



Some surfaces do not have an orientation.

The Möbius strip has no orientation!



If  $S$  has an orientation we say it is orientable, and then  $S$  has precisely two orientations (if it is connected).

Parametrizations  $\Phi: D \rightarrow \mathbb{R}^3$  determine orientations.

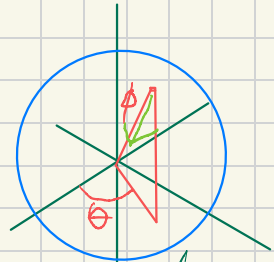
$$\text{Sphere: } \Phi(\theta, \phi) = (\sin \phi \cos \theta, \sin \phi \sin \theta, \cos \phi)$$

$$T_\theta = (-\sin \phi \sin \theta, \sin \phi \cos \theta, 0)$$

$$T_\phi = (\cos \phi \cos \theta, \cos \phi \sin \theta, -\sin \phi)$$

$$T_\theta \times T_\phi = (-\sin^2 \phi \cos \theta, -\sin^2 \phi \sin \theta, -\sin \phi \cos \phi)$$

This normal vector points in to the sphere (because words are  $< 0$ , when  $\theta, \phi$  are small)



More usually we take an outward pointing orientation.

The parametrization  $\Phi_i(\phi, \theta) = (\text{same as at top})$  gives an outward orientation

Cylinder

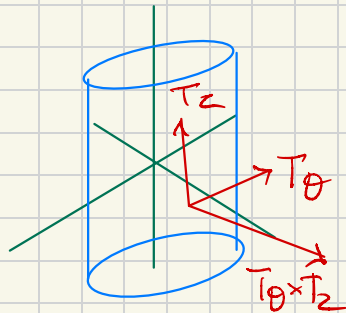
$$\vec{\Phi}(\theta, z) = (\cos\theta, \sin\theta, z)$$

$$\vec{T}_\theta = (-\sin\theta, \cos\theta, 0)$$

$$\vec{T}_z = (0, 0, 1)$$

$$\vec{T}_\theta \times \vec{T}_z = (\cos\theta, \sin\theta, 0)$$

points out.

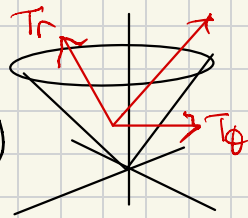


Cone

$$\vec{\Phi}(r, \theta) = (r \cos\theta, r \sin\theta, r)$$

$$0 \leq \theta \leq 2\pi, \quad 0 \leq r$$

Does the orientation determined by Phi point up or down?



- ✓ a. Up
- b. Down
- c. Neither

Example.

Find  $\iint_S \mathbf{F} \cdot d\mathbf{S}$  where  $\mathbf{F}(x,y,z) = (0, 0, z)$  and  $S$  is the part of the cone  $z = \sqrt{x^2 + y^2}$  where  $z \leq 1$ , oriented by a downward pointing normal.

Solution:

Issue: The parametrization

$\Phi(r, \theta) = (r \cos \theta, r \sin \theta, r)$  is wrong for the downward orientation.

Same picture as last page.

2 approaches

1. Do the calculation with  $\Phi$  and multiply by  $-1$  at the end.
2. Get a parametrization with the correct orientation

$$\Phi_1(\theta, r) = (r \cos \theta, r \sin \theta, r)$$

Right-hand rule:

